

Linear groups and computation

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1. Why linear groups?

- Fundamental mathematical model of transformations in science.
- Commonly used representation of groups in group theory and its applications.
- Convenient and efficient way to represent groups in computer.

2. Computing with linear groups

How to represent a group in computer?

- Permutations.
- Matrices over finite fields.
- Generators and relations.

Project. Computing with groups given by a finite set of matrices over an infinite field.

- Develop general methods and techniques for computing with linear groups over an arbitrary infinite field.
- Obtain practical algorithms for solution of fundamental computational problems.
- Design software for computing in this class of groups aimed at solution of mathematical problems by straightforward computing.

History.

- L. Babai, R. Beals et. al.
- G. Nebe, W. Plesken et. al.
- B. Eick, G. Ostheimer et. al. (polycyclic groups).
- A. Cohen, W. de Graaf et. al. (algebraic groups).

Obstacles.

- Undecidability of basic computational problems.
- Complexity issues (e.g. such as growth of size of matrix entries).
- Lack of established methods for computing in this class of groups.

3. Finitely generated linear groups and computing.

3.1 Methods of computing.

3.1.1 Representation in computer: main domains.

Given $G := \langle S \rangle$, $S = \{g_1, \dots, g_r\}$, $g_i \in \text{GL}(n, \mathbb{F})$, $1 \leq i \leq r$, \mathbb{F} is a field. Since G is finitely generated, it is defined over a finitely generated extension of the prime subfield of \mathbb{F} . Moreover

Lemma. For a subfield $\mathbb{P} \subseteq \mathbb{F}$ there exist $x_1, \dots, x_m \in \mathbb{F}$ ($m \geq 0$) algebraically independent over \mathbb{P} such that \mathbb{F} is a finite extension of $\mathbb{P}(x_1, \dots, x_m)$.

Examples: main domains

1. \mathbb{Q} and algebraic number fields.
2. $\mathbb{L} = \mathbb{P}(x_1, \dots, x_m)$, \mathbb{P} is a number field or \mathbb{F}_q .
3. A finite extension of \mathbb{L} .

3.1.2 Method of finite approximation.

Let $G = \langle S \rangle$. Then $G \leq \text{GL}(n, R)$ for a finitely generated integral domain $R \subseteq \mathbb{F}$ determined by the entries of matrices in $S \cup S^{-1}$.

Lemma. R is ‘approximated’ by finite fields, i.e.

- for each maximal ideal ρ of R , R/ρ is a finite field;
- the intersection of maximal ideals of R is zero.

Theorem (Mal’cev). The group G is residually finite. Moreover, G is approximated by matrix groups of degree n over finite fields.

3.1.3 Congruence homomorphism techniques.

Given an ideal $\rho \subseteq R$, define the congruence homomorphism $\varphi_\rho : \text{GL}(n, R) \rightarrow \text{GL}(n, R/\rho)$.

Notation

- $\ker \varphi_\rho := \Gamma_\rho$ (principal congruence subgroup).
- $G \cap \Gamma_\rho := G_\rho$ (congruence subgroup).

Method: Reduction to, e.g, finite fields via construction of a congruence homomorphism φ_ρ such that G_ρ satisfy some special properties.

3.2 What are finitely generated linear groups: classes and structure.

Which algorithms do we need?

- 1 Recognition algorithms, i.e. testing the type of an input group.
- 2 Investigation of the structure and properties of the input group.
- 3 Library of basic functions.

Theorem (J. Tits, 1972). A finitely generated linear group over a field is either solvable-by-finite or it contains a non-cyclic free subgroup.

Theorem (Selberg, Wehrfritz). A finitely generated linear group contains a normal subgroup N of finite index such that the torsion elements of N are all unipotent. In particular, if $\text{char } \mathbb{F} = 0$ then N is torsion-free.

Theorem (Lie-Kolchin-Mal'cev). A linear group G over a field \mathbb{F} is solvable-by-finite iff G contains a unipotent-by-abelian subgroup of finite index.

4. Computing in solvable-by-finite groups.

4.1 Computational analogue of the method of finite approximation.

Theorem. Given a finitely generated subgroup G of $GL(n, R)$ there exist maximal ideals ρ of R such that

- (i) torsion elements of G_ρ are unipotent, i.e. G_ρ is torsion free if $\text{char } R = 0$.
- (ii) G_ρ is unipotent-by-abelian if G is solvable-by-finite.

We call φ_ρ for ρ as above an *W-homomorphism*.

Method.

- 1 Select ρ such that φ_ρ is an W-homomorphism.
- 2 Construct $\varphi_\rho(G)$ (which is a matrix group over the finite field R/ρ).
- 3 Find a (finite) normal generating set N of the kernel G_ρ , i.e. $G_\rho = \langle N \rangle^G$.

Examples: W-homomorphisms.

- Let $\mathbb{F} = \mathbb{Q}$. Then $R = \frac{1}{c} \mathbb{Z}$, $c \in \mathbb{Z}$. Define $\rho = p\mathbb{Z}$, $p \neq 2$, $p \nmid c$. Then φ_ρ is a W-homomorphism; in particular, G_ρ is *torsion-free* (Minkowski).
- Let $\mathbb{F} = \mathbb{Q}(\alpha)$ be a number field, $f(t)$ be the minimal polynomial of α . Then $R = \frac{1}{c} \mathcal{O}$, \mathcal{O} is the ring of integers of $\mathbb{Q}(\alpha)$, $c \in \mathbb{Z}$, $c \neq 0$. If $p > 2$ is a prime dividing neither c nor the discriminant of $f(t)$ then reduction modulo p is a W-homomorphism.
- Let $\mathbb{F} := \mathbb{F}_p(x)$. Then $R = \frac{1}{c} \mathbb{F}_p[x]$, $c = c(x) \in \mathbb{F}_p[x]$. If $\alpha \in \overline{\mathbb{F}_p}$, $c(\alpha) \neq 0$ then reduction modulo $\rho := (x - \alpha)$ is a W-homomorphism.

N.B. We can construct W-homomorphisms for all finitely generated integral domains R .

4.2 Algorithms: recognizing types of groups.

- Testing finiteness.

Method ($\text{char } \mathbb{F} = 0$): test whether the kernel G_ρ of reduction modulo ρ for a W -homomorphism φ_ρ is trivial.

- Testing virtual solvability (computational analogue of the Tits alternative).

Method: for a W -homomorphism φ_ρ test whether $G_\rho = \langle N \rangle^G$ is unipotent-by-abelian (via computing in enveloping algebras).

- Testing solvability, (virtual) nilpotency, testing whether the group is abelian-by-finite, central-by-finite etc.

4.3 Algorithms: investigating structure.

- Finite groups: construct an isomorphic copy over a finite field via \mathbb{W} -homomorphisms, and then apply algorithms for matrix groups over finite fields.
- Solvable-by-finite groups. Motivation: theory of infinite soluble groups. Given a finitely generated solvable-by-finite group over a field \mathbb{F} we can:
 - ▶ Construction of a generating set of the completely reducible (i.e. block-diagonal) part of G . This includes testing whether G is completely reducible and whether G is unipotent (i.e. upper uni-triangular in some basis).
 - ▶ Computing a ‘basis’ of the unipotent radical $U(G)$, i.e. a finite set of matrices T such that torsion-free ranks of $\langle T \rangle$ and $U(G)$ are the same. This includes computing Prüfer rank and torsion free rank of G .
 - ▶ Library of functions for computing with (virtually) nilpotent linear groups: this is a premium class of groups.

Software: Magma package http://magma.maths.usyd.edu.au/magma/handbook/matrix_groups_over_infinite_fields.

5. Next step: computing with non-solvable-by-finite groups.

5.1 What are non- solvable-by-finite groups?

- Ubiquity of non solvable-by-finite groups:
a finitely generated linear group ‘most likely’ is not solvable-by-finite (see e.g. D. Epstein, 1971; R. Aoun, 2011).
- Computational obstacles:
 - ▶ Undecidable basic algorithmic problems:
 - membership test is *decidable* in finitely generated solvable-by-finite subgroups of $GL(n, \mathbb{Q})$ (Kopytov, 1968);
 - membership test is *undecidable* in $SL(4, \mathbb{Z})$ (Michailova, 1958).
 - ▶ Too wide class of groups.
 - ▶ Lack of computational methods.

5.2 Why arithmetic groups ?

A subgroup $H \leq \mathrm{GL}(n, \mathbb{Q})$ of an algebraic \mathbb{Q} -group $\mathcal{G} \leq \mathrm{GL}(n, \mathbb{C})$ is *arithmetic* if H is commensurable with $\mathcal{G}_{\mathbb{Z}} := \mathcal{G} \cap \mathrm{GL}(n, \mathbb{Z})$, i.e., $H \cap \mathcal{G}_{\mathbb{Z}}$ has finite index in both H and $\mathcal{G}_{\mathbb{Z}}$.

N.B. Arithmetic subgroups are finitely generated.

Example. If $\mathcal{G} = \mathrm{SL}(n, \mathbb{C})$ or $\mathrm{Sp}(n, \mathbb{C})$ then finite index subgroups of $\mathrm{SL}(n, \mathbb{Z})$, (resp. $\mathrm{Sp}(n, \mathbb{Z})$) are arithmetic.

Motivation.

- One of the central classes of linear groups.
- Fundamental algorithmic problems are known to be decidable (under some conditions!): Grunewald & Segal, 1980.
- Computing with arithmetic subgroups is currently in high demand (in particular, due to impact on number theory, topology, physics: see, e.g., P. Sarnak, *Notes on thin matrix groups*, preprint, 2012).

5.3 Arithmetic groups with the congruence subgroup property: computing

5.3.1 Set up: congruence subgroup property.

Examples: $SL(n, \mathbb{Q})$ vs $SL(n, \mathbb{Z})$.

- 1 The only proper normal subgroups of $SL(n, \mathbb{Q})$ lie in the finite center consisting of scalar matrices (i.e. $SL(n, \mathbb{Q})$ is ‘close’ to simple).
- 2 $\Gamma_n := SL(n, \mathbb{Z})$ contains infinitely many normal subgroups of finite index. For example, *principal congruence subgroups (PCS)* $\Gamma_{n,m}$ of level m , i.e. kernels of $\varphi_m : SL(n, \mathbb{Z}) \rightarrow SL(n, \mathbb{Z}_m)$; here $\mathbb{Z}_m := \mathbb{Z}/m\mathbb{Z}$.
- 3 $\Gamma_2 := SL(2, \mathbb{Z})$ contains normal subgroups of finite index which do not contain a principal congruence subgroup $\Gamma_{2,m}$ for any m (XIXth century; Klein, Fricke). Moreover, $SL(2, \mathbb{Z})$ contains non-central normal subgroups of infinite index (e.g. $\langle t_{21}(m) \rangle^{\Gamma_n}$ is of infinite index for $m > 5$).

Theorem (Bass, Mennicke et al, 1965-67). Every normal non-central subgroup of $SL(n, \mathbb{Z})$, $n > 2$, contains a principal congruence subgroup $\Gamma_{n,m}$ for some m .

Corollary. Each arithmetic subgroup of $SL(n, \mathbb{Z})$, $n \geq 3$, contains a principal congruence subgroup $\Gamma_{n,m}$ for some m .

In other terms $SL(n, \mathbb{Z})$, $n \geq 3$, satisfies the *congruence subgroup property* (CSP).

Examples. $SL(2, \mathbb{Z})$ does not have CSP, while $SL(n, \mathcal{O}_{\mathbb{F}})$, $n \geq 3$, $Sp(2n, \mathcal{O}_{\mathbb{F}})$, $n \geq 2$, satisfy CSP, $\mathcal{O}_{\mathbb{F}}$ is ring of integers of a number field \mathbb{F} that is not totally imaginary.

For details see current surveys on the *congruence subgroup problem*.

5.3.2 Approach to computing with arithmetic subgroups which satisfy CSP.

- (i) Find a principal congruence subgroup $\Gamma_{n,m}$ of H ;
- (ii) Reduce computing to matrix groups over \mathbb{Z}_m .

N.B. A principal congruence subgroup $\Gamma_{n,m}$ of H is not unique, but the maximal PCS $\Gamma_{n,M}$ is unique.

5.4 Structure of arithmetic subgroups and computing

5.4.1 Principal congruence subgroup and computing

Notation. Let $t_{ij} = 1_n + e_{ij}(m)$ be an elementary matrix of level m , $i \neq j$; here $e_{ij}(m)$ is $n \times n$ matrix with m in position (i, j) and zeros everywhere else.

Denote $E_{n,m} = \langle t_{ij}(m) \mid 1 \leq i, j \leq n, i \neq j \rangle$ elementary group of level m .

Properties of $\Gamma_{n,m}$.

Fact 1. $\Gamma_{n,m} = \langle E_{n,m} \rangle^{\Gamma_n}$.

Fact 2. $\Gamma_{n,m^2} \leq E_{n,m}$.

Fact 3. If $|\Gamma_n : H| \leq c$ then $H \geq \Gamma_{n,m^2}$, $m = \text{lcm}\{1, \dots, c\}$.

Proposition. Construction of a PCS in an arithmetic subgroup of $SL(n, \mathbb{Z})$, $n > 2$, is decidable.

Proof. Follows from Todd-Coxeter procedure and Fact 3. \square

Proposition. Let H be an arithmetic subgroup of $SL(n, \mathbb{Z})$. Then the following problems are decidable.

- Membership test of $g \in SL(n, \mathbb{Z})$ in H .
- Computing an upper bound on the index $|SL(n, \mathbb{Z}) : H|$.

Proof. Computing a PCS of H is decidable. \square

Conclusion. Arithmetic subgroups of $SL(n, \mathbb{Z})$, $n > 2$, are *explicitly given* in terms of Grunewald & Segal.

Hence solution of all decision problems obtained by Grunewald & Segal valid for arithmetic subgroups of $SL(n, \mathbb{Z})$, $n > 2$.

N.B.: most of algorithms of Grunewald & Segal are not practical.

5.4.1 Computing in congruence images: subgroups of $\mathrm{GL}(n, \mathbb{Z}_m)$.

Let $m = p_1^{k_1} \dots p_t^{k_t}$ where p_i are distinct primes and $k_i \geq 1$. Then $\mathrm{GL}(n, \mathbb{Z}_m) \cong \mathrm{GL}(n, \mathbb{Z}_{p_1^{k_1}}) \times \dots \times \mathrm{GL}(n, \mathbb{Z}_{p_t^{k_t}})$.

Denote $K := \{h \in \mathrm{GL}(n, \mathbb{Z}_{p^k}) \mid h \equiv 1_n \pmod{p^{k-1}}\}$ (congruence subgroup of level p^{k-1}). Then K is a (finite) p -group and $\mathrm{GL}(n, \mathbb{Z}_{p^k})/K \cong \mathrm{GL}(n, p)$.

Conclusion: computing with matrix groups over \mathbb{Z}_m is reduced via congruence homomorphism method to computing over finite fields and computing in finite p -groups.

6. Algorithms for computing with arithmetic subgroups

6.1 Computing principal congruence subgroups: from finite approximation to strong approximation.

Aim. Find the level M of the maximal principal congruence subgroup of an arithmetic subgroup H of $\Gamma_n := \mathrm{SL}(n, \mathbb{Z})$, $n > 2$.

Feature. The method requires computing congruence images of H modulo all primes.

N.B.: no need for a generating set of the principal congruence subgroup $\Gamma_{n,M}$, although we can compute it too.

What is the strong approximation?

Example: $\mathrm{GL}(n, \mathbb{Z})$ vs $\mathrm{SL}(n, \mathbb{Z})$.

- $\mathrm{GL}(n, \mathbb{Z})$ does not surject onto $\mathrm{GL}(n, p)$ modulo all primes $p \geq 5$.
- $\mathrm{SL}(n, \mathbb{Z})$ surjects onto $\mathrm{SL}(n, p)$ modulo all primes.

Let H be an arithmetic subgroup of $\mathrm{SL}(n, \mathbb{Z})$, $n > 2$.

Fact 1. H surjects onto $\mathrm{SL}(n, p)$ modulo all but a finite number of primes p .

Reason: H is Zariski dense in SL_n (strong approximation theorem).

Moreover

Fact 2. H surjects onto $\mathrm{SL}(n, p)$ iff p does not divide the level M of the maximal principal congruence subgroup of H (besides small exceptions for $n = 3, 4, p = 2$).

These provide fast algorithms for computing the level M of the maximal principal congruence subgroup of H .

6.2 Algorithms: library of functions

6.2.1 Computing the level and related procedures

Given: arithmetic subgroup H of $SL(n, \mathbb{Z})$.

`LevelMaxPCS(H)`: computes the level M of the maximal principal congruence subgroup $\Gamma_{n,M}$ of H .

`IsIn(H, g)`: membership test of $g \in \Gamma_n$ in H .

`Index($\Gamma_n : H$)`: computing the index.

6.2.1 Subnormal structure

`IsSubnormal(H)`: tests whether H is subnormal in Γ_n .

`Normalizer(H)`: returns a generating set of $N_{\Gamma_n}(H)$.

`NormalClosure(H)`: returns a generating set of $\langle H \rangle^{\Gamma_n}$.

`IsSL(H)`: tests whether $H = \text{SL}(n, \mathbb{Z})$.

6.2.3 Orbit-stabilizer problem

Given an arithmetic subgroup H of $SL(n, \mathbb{Z})$, and vectors $u, v \in \mathbb{Q}^n$.

`Orbit(H, u, v)`: tests whether $\exists g \in H$ such that $g(u) = v$ and find a g if such exists.

`Stabilizer(H, u)`: returns a generating set of $\text{Stab}_H(u)$.

N.B.: $\text{Stab}_H(u)$ is a finitely generated group.

Method: solution of orbit-stabilizer problem for $\varphi_m(H)$ acting on \mathbb{Z}^n and $\Gamma_{n,m} \leq H$.

Details: see in Section 4 in Journal of Algebra 421 (2015) 234-259.

6.3 Applications and experimental results

6.3.1 Arithmetic groups and low dimensional topology.

Example(Long & Reid, 2011). Define $\beta_T(F) = \langle X_T, Y_T \rangle \leq \mathrm{SL}(3, \mathbb{Z})$, where

$$X_T = \begin{bmatrix} -1 + T^3 & -T & T^2 \\ 0 & -1 & 2T \\ -T & 0 & 1 \end{bmatrix}, Y_T = \begin{bmatrix} -1 & 0 & 0 \\ -T^2 & 1 & -T \\ T & 0 & -1 \end{bmatrix}, T \in \mathbb{Z}.$$

Theorem (Long & Reid, 2011) Fix an integer $T \neq 0$. Then the groups $\beta_T(F)$ are arithmetic and $\bigcap_{T>0} \beta_T(F) = 1$.

Problem (Long & Reid): what are the indices $|\mathrm{SL}(3, \mathbb{Z}) : \beta_T(F)|$?

N.B.: $|\mathrm{SL}(3, \mathbb{Z}) : \beta_T(F)| \rightarrow \infty$ as $T \rightarrow \infty$.

T	M	index	t(sec.)
1	5	$2^3 31$	0.3
2	2^5	$2^{20} 3 \cdot 7$	0.7
3	$3^3 73$	$2^5 3^{13} 13 \cdot 1801$	5.8
4	$2^7 23$	$2^{33} 3 \cdot 7^2 11 \cdot 79$	3.5
5	$5^3 367$	$2^4 3^3 5^{10} 13 \cdot 31 \cdot 61 \cdot 3463$	62.8
11	$5 \cdot 11^3 797$	$2^6 3 \cdot 5^2 7 \cdot 11^{10} 19 \cdot 31 \cdot 157 \cdot 199 \cdot 4051$	616.4
15	$3^3 5^3 67 \cdot 151$	$2^9 3^{15} 5^{12} 7^3 11 \cdot 13 \cdot 31^2 1093$	56.4
19	$19^3 67 \cdot 307$	$2^4 3^{10} 5 \cdot 7^2 11 \cdot 17 \cdot 19^{10} 31 \cdot 43 \cdot 127 \cdot 733$	108.1
50	$2^5 5^6 23 \cdot 1019$	$2^{27} 3^2 5^{25} 7^3 11 \cdot 31 \cdot 79 \cdot 509 \cdot 148483$	1137.9
100	$2^7 5^6 29 \cdot 67 \cdot 193$	$2^{46} 3^6 5^{25} 7^5 11 \cdot 13 \cdot 31^2 67 \cdot 1783$	186.2

6.3.2 Computing with monodromy groups.

Let

$$U := \begin{bmatrix} 1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ d & d & 1 & 0 \\ 0 & -k & -1 & 1 \end{bmatrix}, \quad T := \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

with $d, k \in \mathbb{Z}$. Then $G(d, k) \leq \mathrm{Sp}(4, \mathbb{Z})$ is the monodromy group of a generalized hypergeometric ordinary differential equation.

For 14 pairs (d, k) the group $G(d, k)$ is a monodromy group associated to Calabi-Yau threefolds; seven of these are arithmetic while the rest are ‘thin’.

Problem (D. van Straten et. al.).

Find an arithmetic subgroup $\hat{G}(d, k)$ of $\mathrm{Sp}(4, \mathbb{Z})$ which contains $G(d, k)$, and compute the index $|\mathrm{Sp}(4, \mathbb{Z}) : \hat{G}(d, k)|$.

(d, k)	M	index	t(sec)
(1, 3)	2	6	3.910
(1, 2)	2	10	3.306
(2, 3)	8	$2^6 \cdot 3 \cdot 5$	4.797
(3, 4)	$2^2 \cdot 3^2$	$2^9 \cdot 3^5 \cdot 5^2$	7.155
(4, 4)	2^6	$2^{20} \cdot 3^2 \cdot 5$	8.064
(6, 5)	$2^3 \cdot 3^2$	$2^{10} \cdot 3^6 \cdot 5^2$	9.988
(9, 6)	$2 \cdot 3^5$	$2^8 \cdot 3^{14} \cdot 5^2$	10.671
(5, 5)	$2 \cdot 5^3$	$2^8 \cdot 3^3 \cdot 5^8 \cdot 13$	10.312
(2, 4)	2^4	$2^{11} \cdot 3^2 \cdot 5$	5.106
(1, 4)	2^2	$2^5 \cdot 5$	3.515
(16, 8)	2^{10}	$2^{40} \cdot 3^2 \cdot 5$	16.841
(12, 7)	$2^5 \cdot 3^2$	$2^{17} \cdot 3^6 \cdot 5^2$	21.446
(8, 6)	2^7	$2^{24} \cdot 3^2 \cdot 5$	10.771
(4, 5)	2^5	$2^{13} \cdot 3 \cdot 5$	7.605